

**Amendment and Response Under 37 C.F.R. 1.116**

Applicant: Thomas A. Saksa

Serial No.: 09/940.363

Filed: August 27, 2001

Docket No.: 10011180-1

Title: MEASUREMENT AND MARKING DEVICE

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**REMARKS**

The following remarks are made in response to the Final Office Action mailed January 24, 2003, in which claims 1-9, 12-16, 18-25, and 27-29 were rejected. With this Amendment, claims 1, 14, and 22 have been amended to more particularly point out and distinctly claim the subject matter which Applicant regards as the invention. Claims 1-9, 12-16, 18-25, and 27-29, therefore, remain pending in the application.

Applicant notes that the Examiner has not provided a basis of rejection for claims 12 and 13. Applicant, therefore, respectfully requests that the Examiner consider claims 12 and 13 and provide notification of the reasons for rejection together with such information and references as may be useful in judging the propriety of continuing the prosecution. See M.P.E.P. 707.

**Claim Rejections under 35 U.S.C. § 102 and § 103**

Claims 1-6, 8, 9, 14-16, 19-25, and 28-29 are rejected under 35 U.S.C. 102(b) as being anticipated by the Coulter U.S. Patent No. 4,233,749. Claims 7, 18, and 27 are rejected under 35 U.S.C. 103(a) as being unpatentable over the Coulter et al. patent in view of the Weber et al. U.S. Patent No. 4,412,232.

With this Amendment, independent claim 1 has been amended to clarify that the housing includes a first opening formed in the first side and a second opening formed in the first side, and that the positional sensing assembly communicates with the first side of the housing through the first opening and the printhead assembly communicates with the first side of the housing through the second opening. In addition, independent claims 14 and 22 have been amended to clarify that sensing the position of the housing includes sensing the position of the housing relative to the object with a positional sensing assembly mounted in the housing and communicated with the first side of the housing through a first opening in the first side of the housing, and that printing the measurement marking includes printing the measurement marking on the surface of the object with a printhead assembly mounted in the housing and communicated with the first side of the housing through a second opening in the first side of the housing.

With respect to the Coulter et al. patent, this patent does not teach or suggest a measurement and marking device, as claimed in claim 1, wherein the housing includes a first

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opening formed in the first side and a second opening formed in the first side wherein the positional sensing assembly communicates with the first side of the housing through the first opening and the printhead assembly communicates with the first side of the housing through the second opening, nor a method of printing a measurement marking on an object, as claimed in claim 14, or a method of transferring a measurement, as claimed in claim 22, wherein sensing the position of the housing includes sensing the position of the housing relative to the object with a positional sensing assembly mounted in the housing and communicated with the first side of the housing through a first opening in the first side of the housing, and wherein printing the measurement marking includes printing the measurement marking on the surface of the object with a printhead assembly mounted in the housing and communicated with the first side of the housing through a second opening in the first side of the housing.

In view of the above, Applicant submits that independent claims 1, 14, and 22 are patentably distinct from the Coulter et al. patent and, therefore, in a condition for allowance. Furthermore, as dependent claims 2-9, 12, and 13 further define patentably distinct claim 1, dependent claims 15, 16, and 18-21 further define patentably distinct claim 14, and dependent claims 23-25 and 27-29 further define patentably distinct claim 22, Applicant submits that dependent claims 2-9, 12, 13, 15, 16, 18-21, 23-25, and 27-29 are also in condition for allowance. Applicant, therefore, respectfully requests that the rejection of claims 1-6, 8, 9, 14-16, 19-25, and 28-29 under 35 U.S.C. 102(b) and claims 7, 18, and 27 under 35 U.S.C. 103(a) be reconsidered and withdrawn and that claims 1-9, 12-16, 18-25, and 27-29 be allowed.

**CONCLUSION**

In view of the above, Applicant respectfully submits that pending claims 1-9, 12-16, 18-25, and 27-29 are all in condition for allowance and requests reconsideration of the application and allowance of all pending claims.

Attached hereto is a marked-up version of the changes made to the specification and/or the claims by the current Amendment. The attached pages are captioned "**VERSION WITH MARKINGS TO SHOW CHANGES MADE**".

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Any inquiry regarding this Amendment and Response should be directed to Gregg W. Wisdom at Telephone No. (360) 212-8052, Facsimile No. (360) 212-3060. In addition, all correspondence should continue to be directed to the following address:

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Respectfully submitted,

Thomas A. Saksa,

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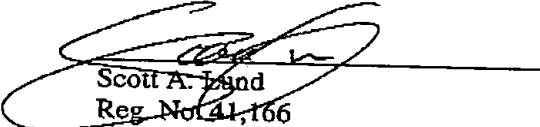
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Date: MARCH 19, 2003  
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CERTIFICATE OF DEPOSIT	
The undersigned hereby certifies that this paper or papers as described herein, are being facsimile transmitted to the United States Patent and Trademark Office, File No. (09/940,363) on the 19th day of March, 2003.	
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**EXPEDITED PROCEDURE**  
**Examining Group Number 2859**

**IN THE UNITED STATES PATENT AND TRADEMARK OFFICE**

Applicant:	Thomas A. Saksa	Examiner:	Amy R. Cohen
Serial No.:	09/940,363	Group Art Unit:	2859
Filed:	August 27, 2001	Docket No.:	10011180-1
Title:	MEASUREMENT AND MARKING DEVICE		

**AMENDMENT AND RESPONSE UNDER 37 C.F.R. 1.116**

Box AF  
Commissioner for Patents  
Washington, D.C. 20231

Dear Sir/Madam:

**VERSION WITH MARKINGS  
TO SHOW CHANGES MADE**

This Amendment and Response is in reply to the Final Office Action mailed January 24, 2003. Applicant respectfully requests entry of this Amendment and is proposing this Amendment to place the application in a condition for allowance. Please amend the above-identified patent application as follows:

**IN THE CLAIMS**

Please amend claims 1, 14, and 22 as follows:

1. (Amended) A measurement and marking device, comprising:
  - a housing;
  - a positional sensing assembly mounted in the housing and adapted to sense a position of the housing relative to an object as the housing is moved along a surface of the object;
  - a printhead assembly mounted in the housing and adapted to print on the surface of the object as the housing is moved along the surface of the object; and
  - a controller mounted in the housing and communicating with the positional sensing assembly and the printhead assembly, wherein the controller is adapted to operate the printhead assembly to print a mark on the surface of the object based on the position of the housing relative to the object as the housing is moved along the surface of the object,
  - wherein the housing has a first side adapted to be oriented substantially parallel with the surface of the object as the housing is moved along the surface of the object and includes a first opening formed in the first side and a second opening formed in the first side,

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wherein the positional sensing assembly communicates with the first side of the housing through the first opening and the printhead assembly communicates with the first side of the housing through the second opening.

2. The measurement and marking device of claim 1, wherein the positional sensing assembly is adapted to sense a position of the housing relative to a first object and measure a dimension of the first object as the housing is moved along a surface of the first object, wherein the positional sensing assembly is adapted to sense a position of the housing relative to a second object as the housing is moved along a surface of the second object, and wherein the controller is adapted to operate the printhead assembly to print the mark on the surface of the second object based on the dimension of the first object and the position of the housing relative to the second object as the housing is moved along the surface of the second object.

3. The measurement and marking device of claim 2, further comprising:  
a user interface mounted on the housing and communicating with the controller,  
wherein the user interface includes an input configured for operation by a user of the measurement and marking device,  
wherein the controller is adapted to record the position of the housing relative to the first object when the input is operated by the user.

4. The measurement and marking device of claim 3, wherein the controller is adapted to operate the printhead assembly to print the mark on the surface of the second object based on the position of the housing relative to the first object when the input is operated by the user and the position of the housing relative to the second object as the housing is moved along the surface of the second object.

5. The measurement and marking device of claim 1, wherein the controller is adapted to operate the printhead assembly to print a plurality of markings on the surface of the object at predetermined intervals as the housing is moved along the surface of the object.

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6. The measurement and marking device of claim 5, wherein the plurality of markings represent one of standard measurements and scaled measurements.
7. The measurement and marking device of claim 1, wherein the printhead assembly is adapted to print at least one of graphics and text on the surface of the object as the housing is moved along the surface of the object.
8. The measurement and marking device of claim 1, wherein the positional sensing assembly includes a wheel rotatably mounted in the housing, wherein the wheel is adapted to contact the surface of the object and rotate as the housing is moved along the surface of the object, and wherein the controller is adapted to determine the position of the housing relative to the object based on rotation of the wheel.
9. The measurement and marking device of claim 1, wherein the positional sensing assembly includes an optical sensor mounted in the housing, wherein the optical sensor is adapted to sense the surface of the object as the housing is moved along the surface of the object, and wherein the controller is adapted to determine the position of the housing relative to the object based on the surface of the object.
10. (Previously Cancelled)
11. (Previously Cancelled)
12. The measurement and marking device of claim 1, wherein the printhead assembly includes a plurality of orifices formed in a front face thereof, wherein the front face communicates with the first side of the housing.
13. The measurement and marking device of claim 1, further comprising:  
a power supply mounted in the housing, wherein the power supply supplies power to the measurement and marking device.

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14. (Amended) A method of printing a measurement marking on an object, the method comprising the steps of:

moving a housing along a surface of the object, including orienting a first side of the housing substantially parallel with the surface of the object;

sensing a position of the housing relative to the object with a positional sensing assembly mounted in the housing and communicated with the first side of the housing through a first opening in the first side of the housing; and

printing the measurement marking on the surface of the object with a printhead assembly mounted in the housing and communicated with the first side of the housing through a second opening in the first side of the housing when the position of the housing relative to the object corresponds to a predetermined position.

15. The method of claim 14, wherein the step of printing the measurement marking on the surface of the object includes printing a plurality of measurement markings on the surface of the object at predetermined intervals.

16. The method of claim 15, wherein printing the plurality of measurement markings includes printing one of a plurality of standard length units and a plurality of scaled length units on the surface of the object.

17. (Previously Cancelled)

18. The method of claim 14, wherein the step of printing the measurement marking on the surface of the object includes printing at least one of graphics and text on the surface of the object.

19. The method of claim 14, further comprising the step of:

receiving and storing the predetermined position of the housing for printing the measurement marking at a controller mounted within the housing.

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20. The method of claim 14, wherein the step of moving the housing along the surface of the object includes contacting the surface of the object with a wheel rotatably mounted in the housing and rotating the wheel relative to the housing, and wherein the step of sensing the position of the housing includes determining the position of the housing relative to the object based on rotation of the wheel.

21. The method of claim 14, wherein the step of moving the housing along the surface of the object includes sensing the surface of the object with an optical sensor mounted in the housing, and wherein the step of sensing the position of the housing includes determining the position of the housing relative to the object based on the surface of the object.

22. (Amended) A method of transferring a measurement of a first object to a second object, the method comprising the steps of:

moving a housing along a surface of the first object, including orienting a first side of the housing substantially parallel with the surface of the first object;

sensing a position of the housing relative to the first object with a positional sensing assembly mounted in the housing and communicated with the first side of the housing through a first opening in the first side of the housing as the housing is moved along the surface of the first object;

locating a feature of the first object, including recording the position of the housing at the feature of the first object;

moving the housing along a surface of the second object, including orienting the first side of the housing substantially parallel with the surface of the second object;

sensing a position of the housing relative to the second object with the positional sensing assembly as the housing is moved along the surface of the second object; and

printing a mark representing the feature of the first object on the surface of the second object with a printhead assembly mounted in the housing and communicated with the first side of the housing through a second opening in the first side of the housing when the position of the housing relative to the second object coincides with the position of the housing at the feature of the first object.



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23. The method of claim 22, wherein the step of sensing the position of the housing relative to the first object includes measuring a dimension of the first object, wherein the step of locating the feature of the first object includes measuring at least one of a dimension to the feature of the first object and a dimension of the feature of the first object, and wherein the step of printing the mark on the surface of the second object includes printing the mark on the surface of the second object when the position of the housing relative to the second object coincides with the at least one of the dimension to the feature of the first object and the dimension of the feature of the first object.

24. The method of claim 22, wherein the step of locating the feature of the first object includes receiving a user input at the position of the housing at the feature of the first object.

25. The method of claim 24, wherein recording the position of the housing at the feature of the first object includes storing the position of the housing at the feature of the first object with the user input in a controller mounted in the housing.

26. (Previously Cancelled)

27. The method of claim 22, wherein the step of printing the mark on the surface of the second object includes printing at least one of graphics and text on the surface of the second object.

28. The method of claim 22, wherein the steps of moving the housing along the surface of the first object and the surface of the second object each include contacting the surface of the first object and the surface of the second object with a wheel rotatably mounted in the housing and rotating the wheel, wherein the steps of sensing the position of the housing relative to the first object and the second object each include determining the position of the housing relative to the first object and the second object based on rotation of the wheel.

29. The method of claim 22, wherein the steps of moving the housing along the surface of the first object and the surface of the second object each include sensing the surface of the

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first object and the surface of the second object with an optical sensor mounted in the housing, and wherein the steps of sensing the position of the housing relative to the first object and the second object each include determining the position of the housing relative to the first object and the second object based on the surface of the first object and the surface of the second object, respectively.

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